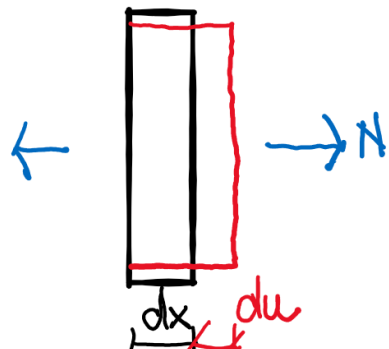


# CÁLCULO DE DESPLAZAMIENTOS

## Deformaciones

### AXIL

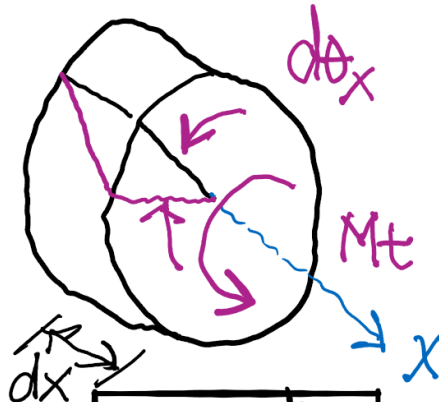


$$\epsilon_x = du/dx$$

$$\sigma_x = N/A = \epsilon_x \cdot E$$

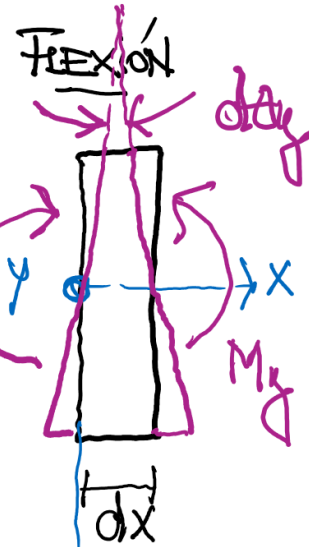
$$\epsilon_x = \frac{N}{EA}$$

### Torsión



$$\gamma_x = \frac{d\theta_x}{dx}$$

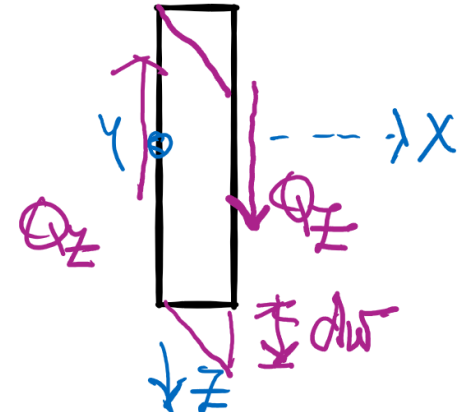
$$\gamma_{\theta x} = \frac{Mt}{G \cdot J_p}$$



$$\gamma_{\theta y} = \frac{d\delta_y}{dx}$$

$$\gamma_{\theta y} = \frac{M_y}{E \cdot J_y}$$

### CORTE



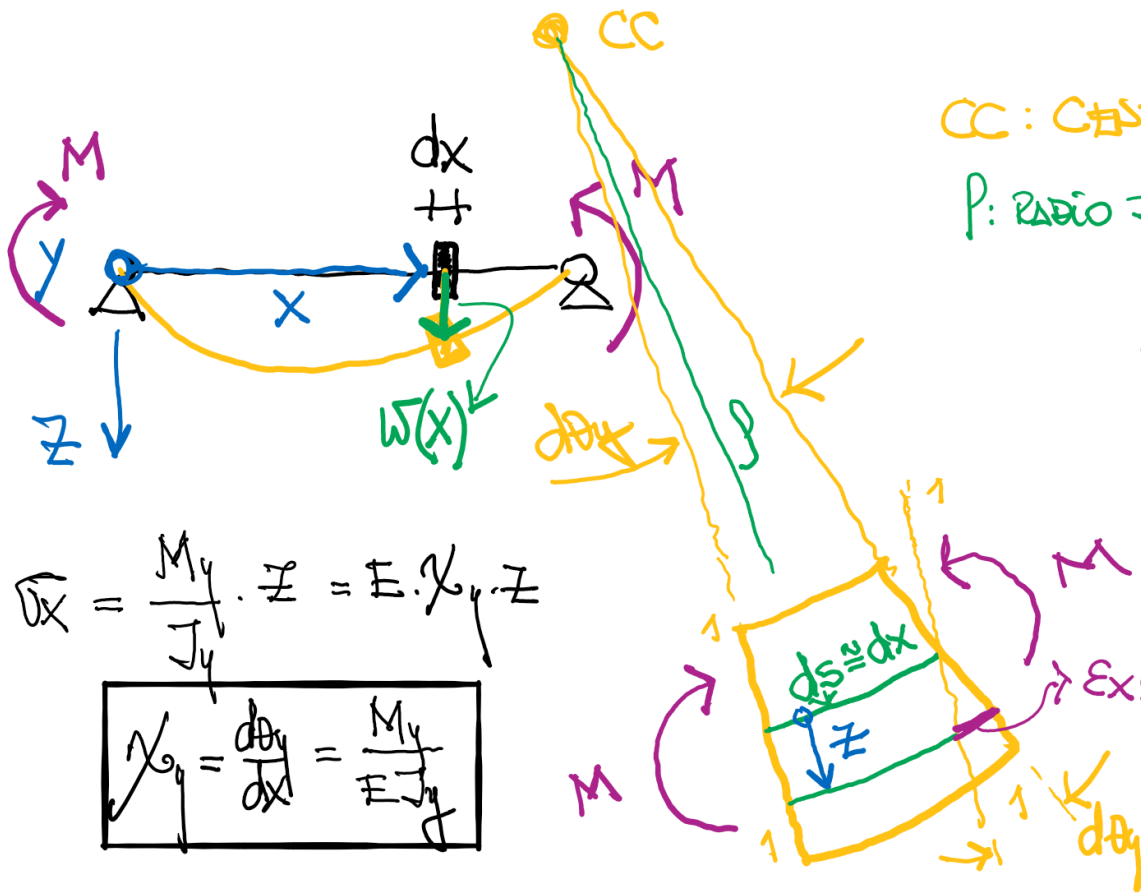
$$\frac{d\omega}{dx} = \frac{Q_z}{G \cdot A} \cdot K_z$$

$$A_R = \frac{A}{K_z}$$

FACTOR DE FORMA

Se deforma conservando la dirección del eje

Se deforma en la dirección transversal al eje de barra - EJE CURVO



CC: CENTRO DE CURVATURA

P: RADIO DE CURVATURA

$$\rho = \frac{1}{\kappa} \rightarrow \kappa = \frac{d\theta_y}{dx} = \frac{1}{\rho}$$

$$\left. \begin{aligned} \rho \cdot d\theta_y &= dx \\ z \cdot d\theta_y &= \epsilon_x \cdot dx \end{aligned} \right\}$$

$$z \frac{d\theta_y}{dx} = \epsilon_x = z \cdot \kappa$$

$$\sigma_x = E \epsilon_x = E \cdot \kappa \cdot z$$

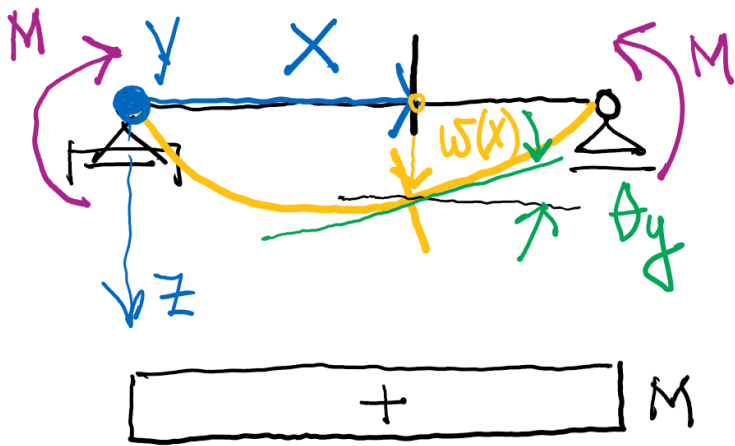
$$\sigma_x = \frac{M_y}{J_y} \cdot z = E \cdot \kappa \cdot z$$

$$\kappa = \frac{d\theta_y}{dx} = \frac{M_y}{E J_y}$$

EXPRESION MATEMATICA DE LA CURVATURA

$$\kappa = \frac{dw^2/dx^2}{\left[1 + \left(\frac{dw}{dx}\right)^2\right]^{3/2}}$$

$$\frac{dw}{dx} = w' \lll 1 \rightarrow w' = 0 \quad \kappa = \frac{d^2w}{dx^2}$$



$$\theta_y \approx \tan \theta_y = \frac{dw(x)}{dx}$$

$$\chi_y = \frac{d\theta_y}{dx} = \frac{d^2 w}{dx^2}$$

$$\chi_y = \frac{M_y}{E \cdot J_y}$$

$$\frac{d^2 w}{dx^2} = - \frac{M_y}{E J_y}$$

CONDICIONES DE BORDE

$$x=0 \rightarrow w(0)=0 \rightarrow C_2=0$$

$$x=L \rightarrow w(L)=0 \rightarrow C_1 = \frac{M_y \cdot L}{2 E J_y}$$

$$w' = - \frac{M_y}{E J_y} \cdot x + C_1$$

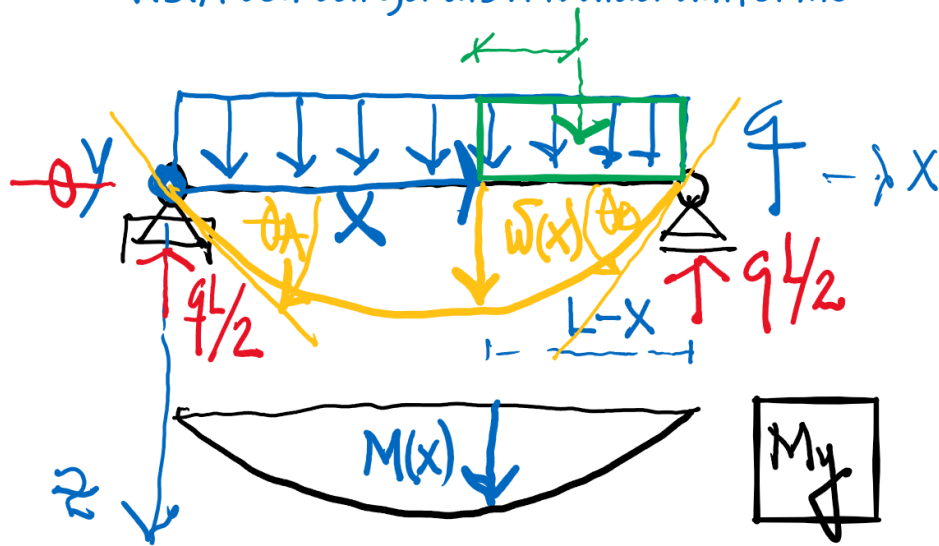
$$w = - \frac{M_y}{E J_y} \cdot \frac{x^2}{2} + C_1 \cdot x + C_2$$

$$w(x) = - \frac{M_y}{E J_y} \cdot \frac{x^2}{2} + \frac{M_y \cdot L}{2 E J_y} \cdot x$$

$$w_{\max} \rightarrow \frac{dw(x)}{dx} = 0 \rightarrow x = \frac{L}{2}$$

$$w_{\max} = \frac{M \cdot L^2}{8 E J_y}$$

V.S.A con carga distribuida uniforme



CONDICIONES DE BORDE

$$X=0 \rightarrow w(0)=0 \rightarrow C_2=0$$

$$X=L \rightarrow w(L)=0 \rightarrow C_1$$

$$\frac{d^2 w}{dx^2} = - \frac{M(x)}{EJ_y}$$

$$M(x) = \frac{qL}{2} \cdot (L-x) - q \cdot \left(\frac{L-x}{2}\right)^2$$

$$M(x) = \frac{q}{2} (L \cdot x - x^2)$$

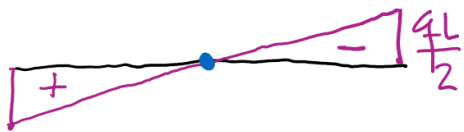
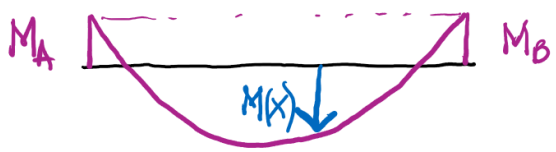
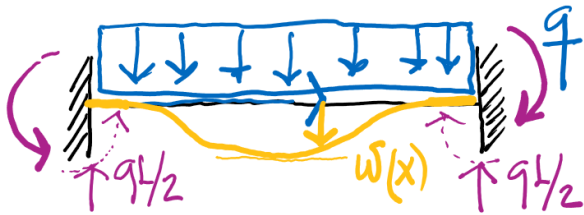
$$w'(x) = - \frac{q}{2EJ_y} \cdot \left( L \frac{x^2}{2} - \frac{x^3}{3} \right) + C_1$$

$$w(x) = - \frac{q}{2EJ_y} \left( L \frac{x^3}{6} - \frac{x^4}{12} \right) + C_1 \cdot x + C_2$$

$$w(x) = \frac{q}{EJ_y} \frac{x^4}{24} - \frac{q}{EJ_y} \cdot L \cdot \frac{x^3}{12} + \frac{q \cdot x \cdot L^3}{24 \cdot EJ_y}$$

$$w_{\max} = w\left(\frac{L}{2}\right) = \frac{5}{384} \frac{q \cdot L^4}{EJ_y} \leq \frac{L}{300} \text{ ó } \frac{L}{500}$$

Ej 3 Viga doblemente empotrada con carga uniformemente distribuida

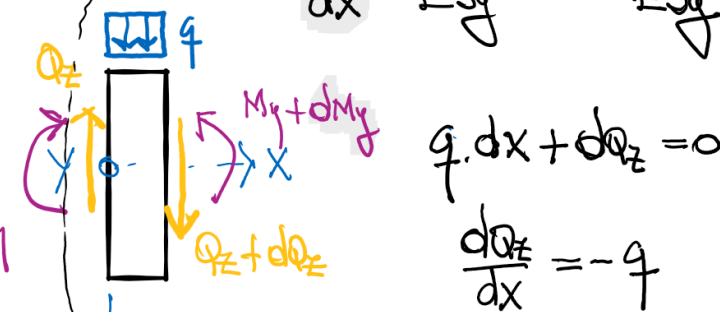


$$w'' = - \frac{M(x)}{EI_y}$$

$$M(x) = ?$$

$$w'''' = - \frac{dM(x)}{dx} \cdot \frac{1}{EI_y} = - \frac{Q_z}{EI_y}$$

$$w'''' = - \frac{dQ_z}{dx} \cdot \frac{1}{EI_y} = + \frac{q}{EI_y}$$



$$q \cdot dx + dQ_z = 0$$

$$\frac{dQ_z}{dx} = -q$$

CONDICIONES DE VINCULO

$X=0 \rightarrow w(0) = 0 \rightarrow w'(0) = 0$

$X=L \rightarrow w(L) = 0 \rightarrow w'(L) = 0$

$X=L/2 \rightarrow w'(L/2) = 0$

$\rightarrow w'''(L/2) = 0$  CORTE

$$w_{max} = \frac{1}{384} \frac{qL^4}{EI_y}$$

CORTE

MOMENTO

GIRO

ELASTICA

$$w''' = + \frac{q}{EI_y} \cdot X + C_1$$

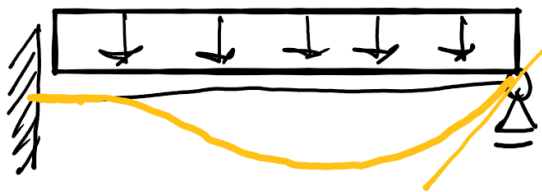
$$w'' = + \frac{q}{EI_y} \cdot \frac{X^2}{2} + C_1 \cdot X + C_2$$

$$w' = + \frac{q}{EI_y} \cdot \frac{X^3}{6} + C_1 \cdot \frac{X^2}{2} + C_2 \cdot X + C_3$$

$$w = + \frac{q}{EI_y} \cdot \frac{X^4}{24} + C_1 \cdot \frac{X^3}{6} + C_2 \cdot \frac{X^2}{2} + C_3 \cdot X + C_4$$

Polinomio de 4to Grado

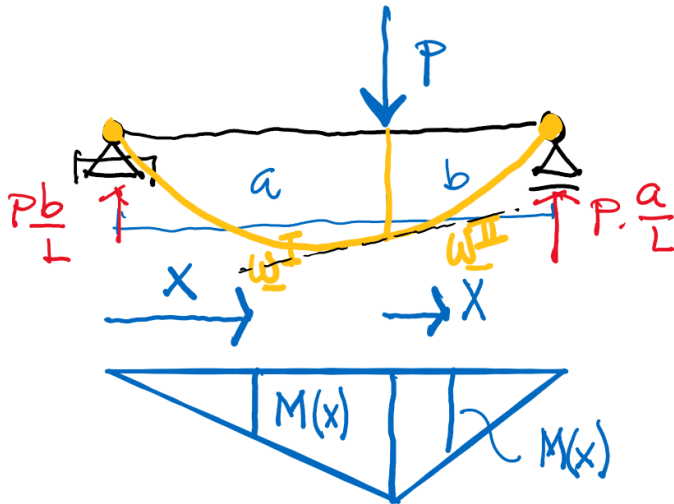
Ej 4 Viga Empotrada / Simplemente apoyada con carga uniforme



$$\begin{aligned} w(0) &= 0 & w'(0) &= 0 \\ w(L) &= 0 & w''(L) &= 0 \end{aligned}$$

Ej VSA con una carga concentrada

$$w''(x) = - \frac{M(x)}{EJ_y}$$

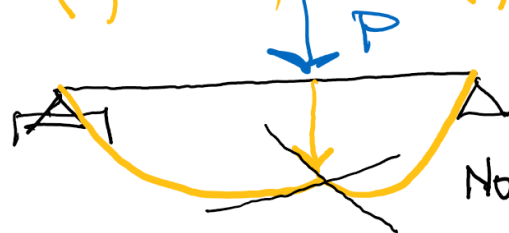


$$\begin{aligned} \text{I} \quad 0 \leq x \leq a & \quad M(x) = P \cdot \frac{b}{L} \cdot x \rightarrow w^{\text{I}} & \begin{cases} C_1 \\ C_2 \end{cases} \\ \text{II} \quad a \leq x \leq L & \quad M(x) = P \cdot \frac{a}{L} (L-x) \rightarrow w^{\text{II}} & \begin{cases} C_3 \\ C_4 \end{cases} \end{aligned}$$

CONDICIONES DE BORDE

$$\begin{aligned} w^{\text{I}}(0) &= 0 & ; & \quad w^{\text{II}}(L) = 0 \\ w^{\text{I}''}(0) &= 0 & ; & \quad w^{\text{II}''}(L) = 0 \end{aligned}$$

$$w^{\text{I}}(a) = w^{\text{II}}(a)$$



$$w^{\text{I}'}(a) = w^{\text{II}'}(a)$$