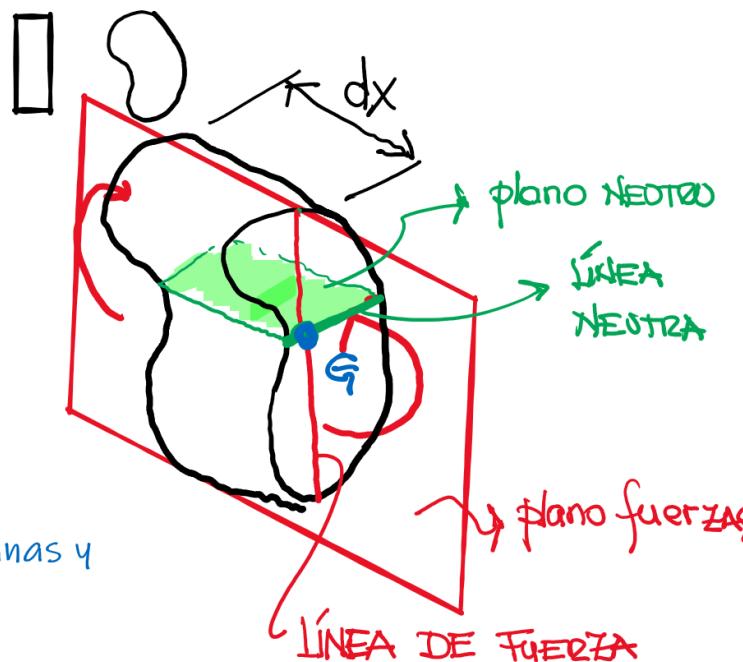
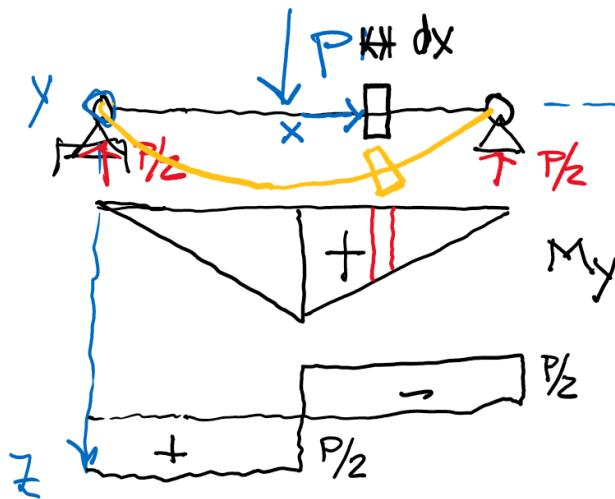
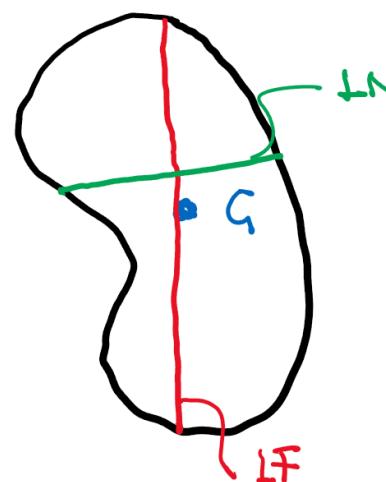
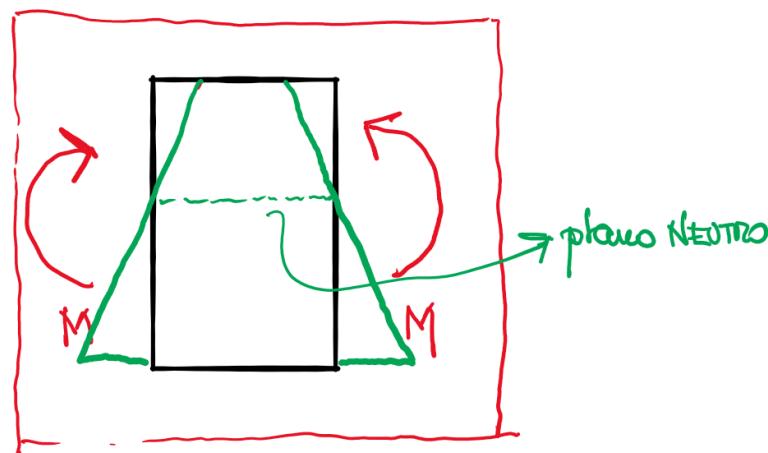


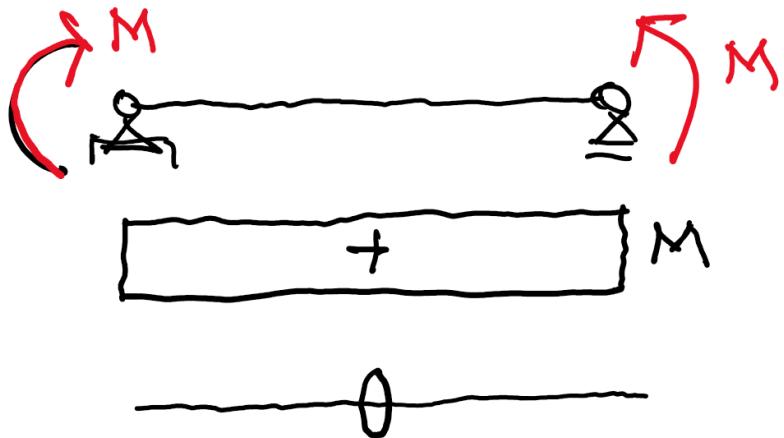
## BARRAS SOLICITADAS A FLEXION



HIPOTESIS: Secciones se mantienen planas y perpendiculares al eje de barra



## clasificación de flexión



Flexión constante

Flexión variable

Flexión Simple

Flexión Compuesta

Flexión RECTA

Flexión OBLICUA

$M \neq 0$      $Q = 0$

$M \neq 0$      $Q \neq 0$

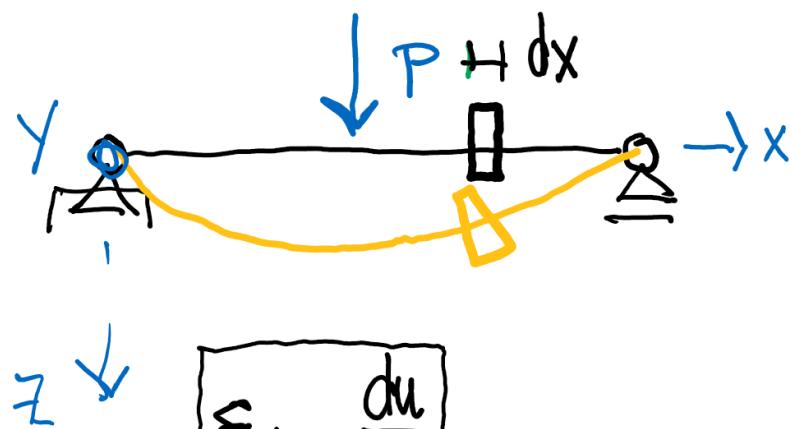
$M \neq 0$      $N = 0$

$M \neq 0$      $N \neq 0$

$M$  coincide con EPI

$M$  NO coincide con EPI

## Estudio de la deformación



$$\epsilon_x = \frac{du}{dx}$$

$$P \cdot d\theta_y = dx$$

$$\kappa_y = \frac{d\theta_y}{dx} = \frac{1}{\rho}$$

CURVATURA

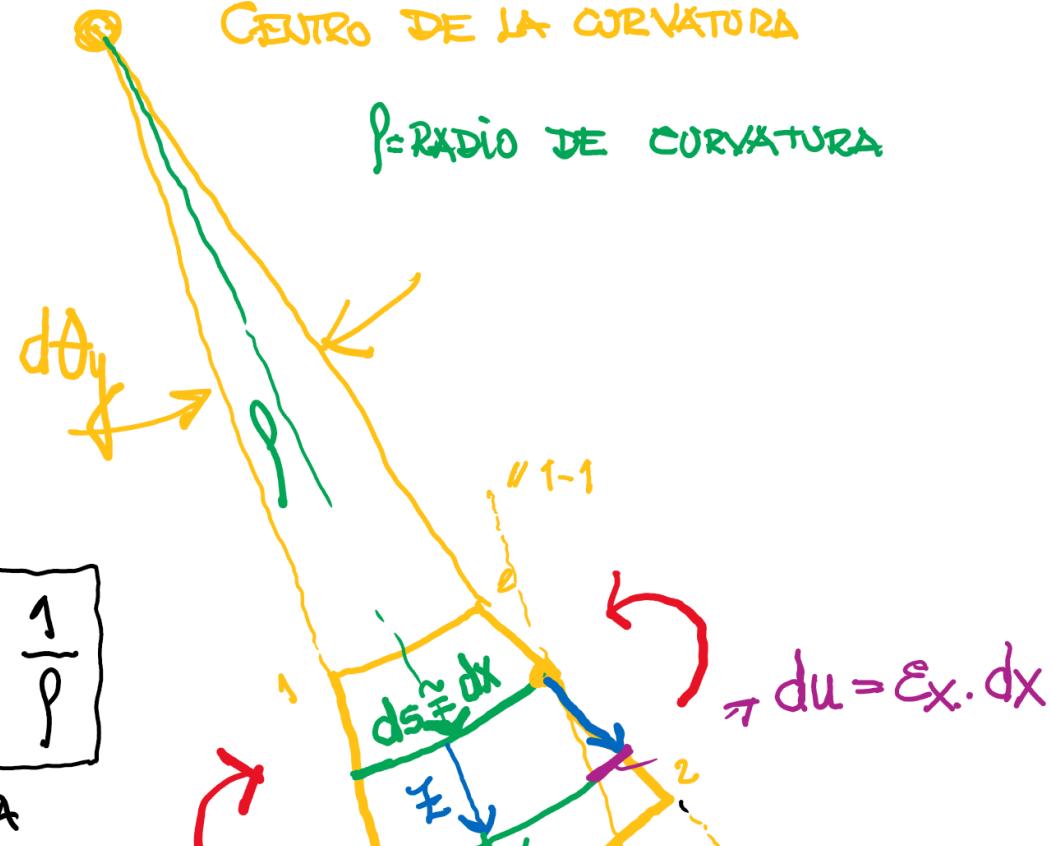
$$z \cdot d\theta_y = du = \epsilon_x \cdot dx$$

$$z \cdot \frac{d\theta_y}{dx} = \epsilon_x = \kappa_y \cdot z$$

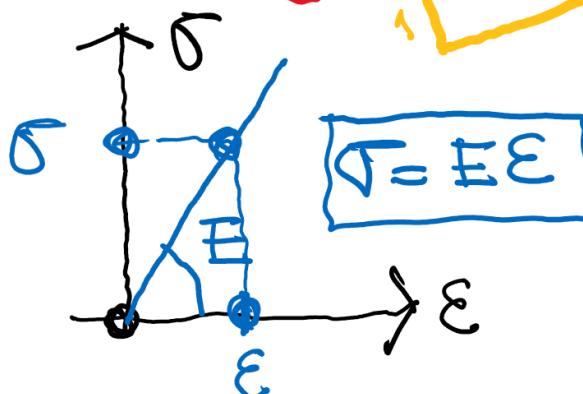
$$\sigma_x = E \cdot \epsilon \cdot z$$

## CENTRO DE LA CURVATURA

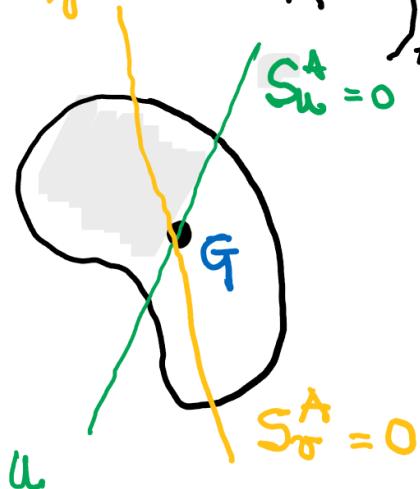
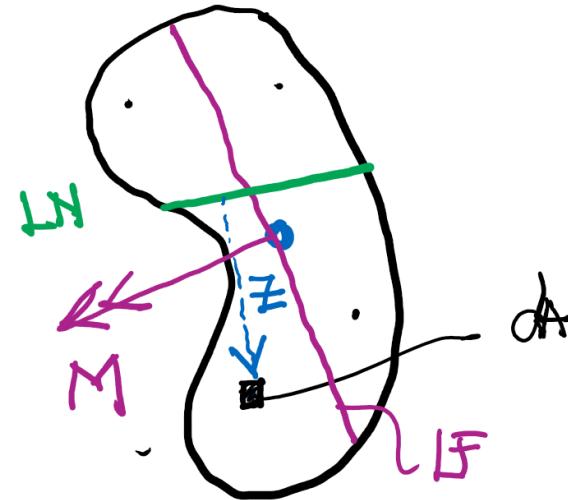
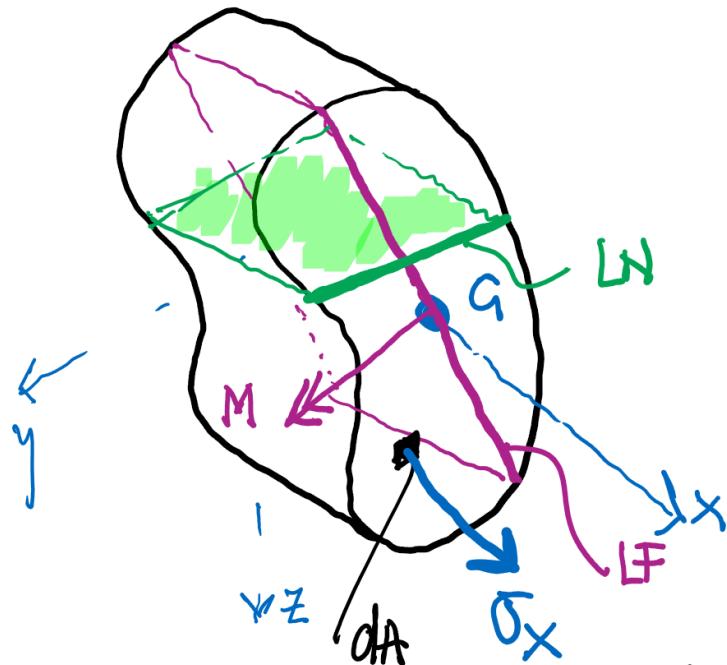
$\rho$  = RÁDIO DE CURVATURA



$$\pi du = \epsilon_x \cdot dx$$



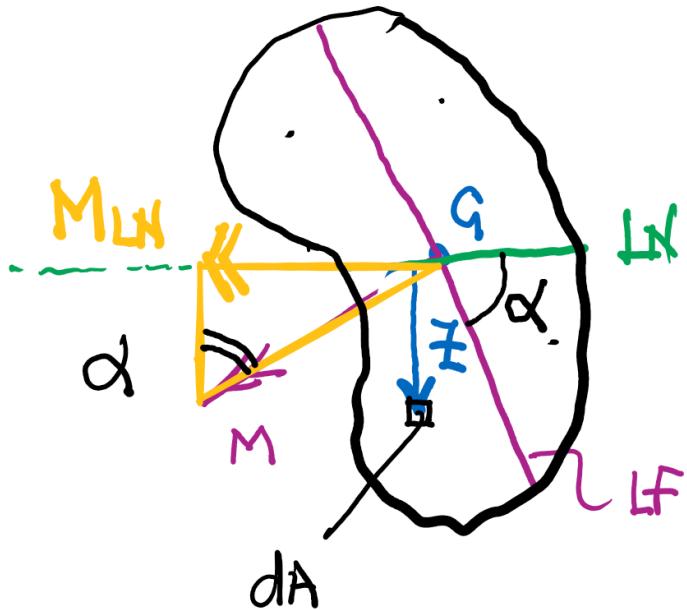
## Ecuaciones de equivalencia



$$N = \int_A \bar{x} \cdot dA = \int_A \pm \chi_y \cdot \mp \cdot dA = \mp \chi_y \int_A \mp \cdot dA = 0$$

LN pasa x G

FLEXIÓN SIMPLE  
 $\Leftrightarrow S_{LN}^A = 0$



$$M_{LN} = \int_A T_x \cdot dA \cdot z = M_{\text{seu } \alpha}$$

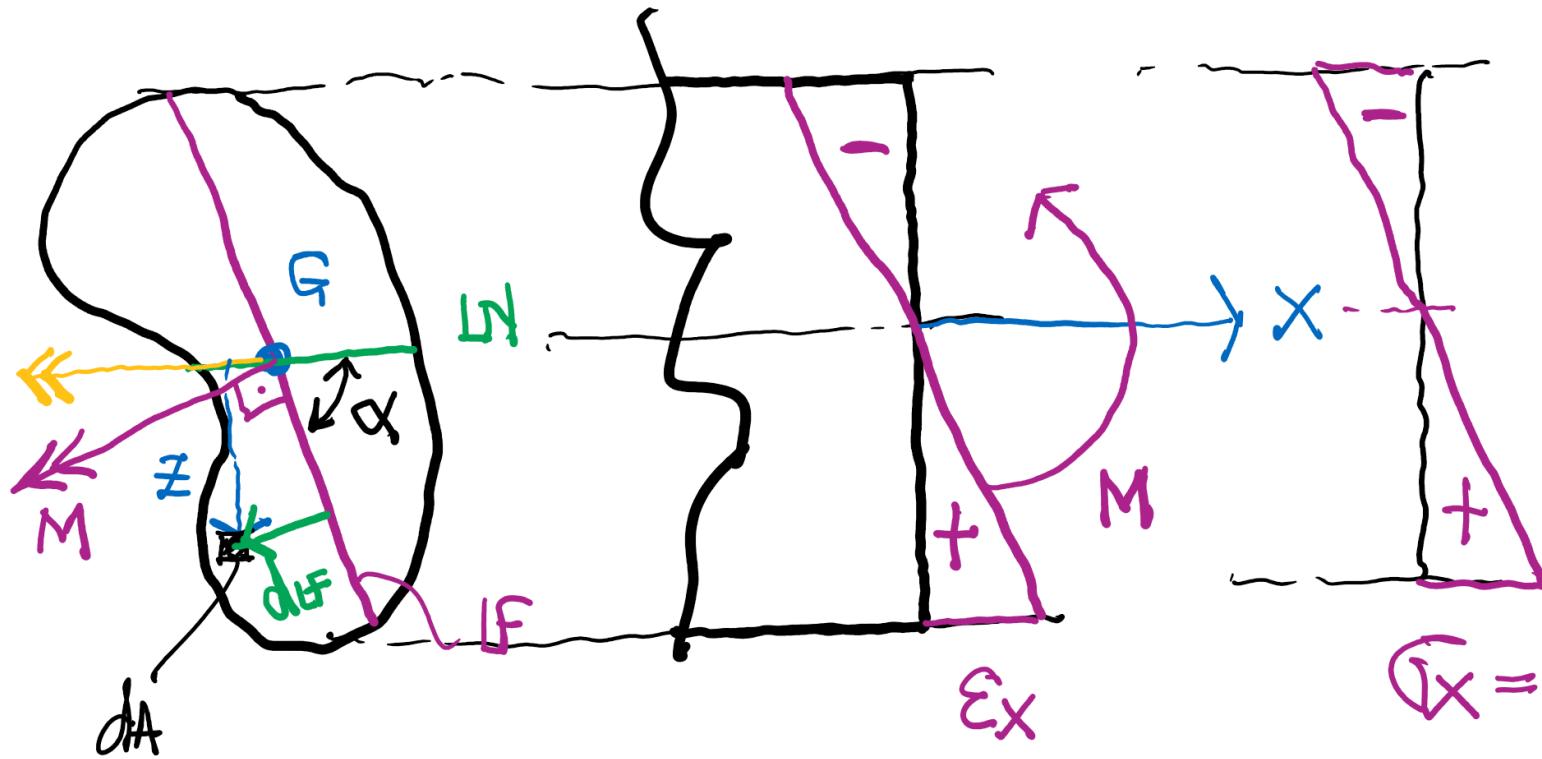
$\alpha$ : áng e/ IF y LN

$$M_{\text{seu } \alpha} = \int_A z \cdot I_y \cdot z^2 \cdot dA = I_y \int_A z^3 dA$$

$$\chi_y = \frac{M_{\text{seu } \alpha}}{\pi \cdot J_{LN}} = \frac{\partial \theta}{\partial x}$$

$J_{LN}$

$$T_x = \frac{M_{\text{seu } \alpha}}{J_{LN}} \cdot z$$



$$F_e = \frac{M_e \cdot \sin \alpha}{J_{LN}}$$

$$M_{LF} = \int_A F_e \cdot dA \cdot d_{LF} = \int_A E \cdot \chi_y \cdot z \cdot d_{LF} \cdot dA = E \chi_y \int_A z \cdot d_{LF} \cdot dA = 0$$

$\text{LN}$  y  $\text{LF}$  SON EJES CONJUGADOS  $\leftarrow J_{\text{LN};LF} = 0$